

# 8051 Codes

Example codes (in C) for the classical Intel-8051 (mcu51) microcontroller core. Using my1code51 library. Tested using sdcc open source compiler and stc12 device.

## Code: IR module and Ultrasonic sensor module

Testing IR module and HC-SR04 ultrasonic sensor module.

test0\_ir\_hc.c

```

/*-----*/
-----*/
#include "uart.h"
#include "timer.h"
#define FPSIZE 2
#include "utils_float.h"
#define _LCD_4BIT_INTERFACE_
/** DB4-DB7 => P0 (UPPER NIBBLE) */
/** E => P0.2 ; NEEDS -ve EDGE */
/** R/W => P0.1 ; 0=WR 1=RD */
/** RS => P0.0 ; 0=CMD 1=DAT */
#include "textlcd.h"
/*-----*/
-----*/
/**
 * Testing IR module and HC-SR04 ultrasonic sensor module
 * - display on both uart and lcd
 */
/*-----*/
-----*/
MY1SBIT(IRMOD,PIN10);
MY1SBIT(TRIG,PIN16);
MY1SBIT(ECHO,PIN17);
/*-----*/
-----*/
MY1SBIT(TEST_IR,PIN14);
MY1SBIT(TEST_HC,PIN15);
/*-----*/
-----*/
#define FLAG_IR 0x01
#define FLAG_HC 0x02
/*-----*/
-----*/
void main(void) {
    unsigned char wait;

```

```

unsigned int tval, loop, flag;
float fval, dist;
char buff[16];
uart_init();
uart_puts("\r\nTESTING NMK322 STUFFS\r\n");
lcd_init();
lcd_goto_line1();
lcd_puts("TESTKIT 4 NMK322");
timer_init();
flag = 0;
while (1) {
    if (TEST_IR==0) {
        if ((flag&FLAG_IR)==0) {
            lcd_goto_line1();
            lcd_puts("TEST 4 IR MODULE");
            uart_puts("\r\nTESTING IR MODULE\r\n");
            flag = FLAG_IR;
        }
        lcd_goto_line2();
        lcd_puts("                ");
        lcd_goto_line2();
        lcd_puts("Waiting... ");
        uart_puts("\r\nWaiting... ");
        while (IRMOD); // outputs logic low when obstacle detected
        lcd_puts("|*");
        uart_puts("|*");
        while (!IRMOD);
        lcd_puts("|");
        uart_puts("| \r\n");
        for (loop=65000; loop; loop--);
    }
    if (TEST_HC==0) {
        if ((flag&FLAG_HC)==0) {
            lcd_goto_line1();
            lcd_puts("TEST HC-SR04 MOD");
            uart_puts("\r\nTESTING HC-SR04 MODULE\r\n");
            flag = FLAG_HC;
        }
        lcd_goto_line2();
        lcd_puts("                ");
        lcd_goto_line2();
        timer_prep(0);
        TRIG = 1;
        for (wait=10; wait; wait--); // around 10us?
        TRIG = 0;
        while (!ECHO); timer_exec();
        while (ECHO); timer_stop();
        tval = ((unsigned int)TH0<<8)|TL0;
        fval = (float)tval * 1.085; // in us
        dist = fval / 58.0; // in cm
        lcd_puts("Dist:");
    }
}

```



```

/*-----*/
-----*/
_sbit(G0000,PIN15);
_sbit(G01MS,PIN16);
_sbit(G02MS,PIN17);
/*-----*/
-----*/
#define BUFFSIZE 128
/*-----*/
-----*/
__xdata char buff[BUFFSIZE];
/*-----*/
-----*/
void uart_show_buff(void) {
    char* pchk = buff;
    while (*pchk) {
        if (pchk[0]<0x20 || pchk[0]>0x7e) {
            uart_puts("[0x");
            uart_send_hexbyte(pchk[0]);
            uart_send(']');
        }
        else uart_send(pchk[0]);
        pchk++;
    }
    uart_send('\n');
}
/*-----*/
-----*/
void main(void) {
    unsigned char curr, test;
    G0000 = 1; G01MS = 1; G02MS = 1;
    timer_init();
    servo_init();
    i2c_init();
    oled1306_init();
    oled1306_puts(APPTITLE);
    uart_init();
    uart_puts("\n-----\n");
    uart_puts(APPTITLE);
    uart_puts("\n-----\n\n");
    hc06_init();
    curr = 3;
    do {
        uart_puts("-- Looking for HC06... ");
        oled1306_set_cursor(OLED_ROW_INF01,0);
        oled1306_puts("Finding HC06... ");
        hc06_find();
        if (hc06_wait_ok()==HC06_OK) {
            uart_puts("OK.\r\n");
            oled1306_puts("OK");
            oled1306_set_cursor(OLED_ROW_INF02,0);

```

```

oled1306_puts("Setting up HC06... ");
uart_puts("\r\nSet default name & pin\r\n");
uart_puts("-- Set Name (");
uart_puts(BTNAME);
uart_puts("): ");
hc06_setname(buff,BUFFSIZE);
uart_puts(buff);
uart_puts("\r\n");
timer_delay1s(test,1);
/* set pass */
uart_puts("-- Set Pin (");
uart_puts(BTPASS);
uart_puts("): ");
hc06_setpin(buff,BUFFSIZE);
uart_puts(buff);
uart_puts("\r\n");
timer_delay1s(test,1);
oled1306_puts("OK");
timer_delay1s(test,1);
oled1306_clear_row(OLED_ROW_INF01);
oled1306_clear_row(OLED_ROW_INF02);
break;
}
uart_puts("timeout.\n");
timer_delay1s(test,1);
} while (--curr);
while (1) {
    if (hc06_peek()) {
        if ((test=hc06_wait(buff,BUFFSIZE))>1) {
            if (buff[0]=='#') {
                if (test==BUFFSIZE) test--;
                buff[test] = 0x0;
                while (buff[test-1]=='\r' || buff[test-1]=='\n') {
                    test--;
                    buff[test] = 0x0;
                }
                curr = (unsigned char) str2uint(&buff[1]);
                if (curr>=5&&curr<=25) {
                    uart_puts("## Turning to (");
                    uart_puts(&buff[1]);
                    uart_puts(")\r\n");
                    oled1306_set_cursor(OLED_ROW_DATA,0);
                    oled1306_puts("ServoTurn: ");
                    oled1306_puts(&buff[1]);
                    servo_turn(curr);
                    timer_delay1s(test,1);
                    oled1306_clear_row(OLED_ROW_DATA);
                }
            }
            else {
                uart_puts("** Invalid angle (");
                uart_puts(&buff[1]);
            }
        }
    }
}

```



```

#define BTNAME "nmk322bt"
#define BTPASS "0000"
#include "hc06.h"
#include "uart.h"
#include "timer.h"
#include "utils.h"
/*-----*/
-----*/
/** interface as defined in nmk322 lab module */
#define _LCD_8BIT_INTERFACE_
#define _LCD_PINS_DEFINED_
MY1SFR(LCD_DATA,0xA0);
MY1SBIT(LCD_BUSY,0xA7);
MY1SBIT(LCD_DNC,0x87);
MY1SBIT(LCD_RNW,0x86);
MY1SBIT(LCD_ENB,0x85);
/*-----*/
-----*/
#include "textlcd.h"
/*-----*/
-----*/
#define SERVO_PIN P1_0
#include "servo.h"
/*-----*/
-----*/
MY1SBIT(G0000,PIN15);
MY1SBIT(G01MS,PIN16);
MY1SBIT(G02MS,PIN17);
/*-----*/
-----*/
#define BUFFSIZE 128
/*-----*/
-----*/
__xdata char buff[BUFFSIZE];
/*-----*/
-----*/
void main(void) {
    unsigned char curr, test;
    G0000 = 1; G01MS = 1; G02MS = 1;
    timer_init();
    servo_init();
    lcd_init();
    lcd_goto_line1();
    lcd_puts("NMK322 SV/LCD/BT");
    uart_init();
    uart_puts("NMK322 SV/LCD/BT\r\n\r\n");
    hc06_init();
    curr = 3;
    do {
        uart_puts("-- Sending AT... ");
        hc06_find();
    }
}

```

```

    if (hc06_wait_ok()==HC06_OK) {
        uart_puts("OK.\r\n");
        uart_puts("\r\nSet default name & pin\r\n");
        uart_puts("-- Set Name (");
        uart_puts(BTNAME);
        uart_puts("): ");
        hc06_setname(buff,BUFFSIZE);
        uart_puts(buff);
        uart_puts("\r\n");
        timer_delay1s(test,1);
        /* set pass */
        uart_puts("-- Set Pin (");
        uart_puts(BTPASS);
        uart_puts("): ");
        hc06_setpin(buff,BUFFSIZE);
        uart_puts(buff);
        uart_puts("\r\n");
        timer_delay1s(test,1);
        break;
    }
    uart_puts("timeout.\n");
    timer_delay1s(test,1);
} while (--curr);
while (1) {
    if (hc06_peek()) {
        if (hc06_wait(buff,BUFFSIZE)>1) {
            if (buff[0]=='#') {
                curr = (unsigned char) str2uint(&buff[1]);
                if (curr>=5&&curr<=25) {
                    uart_puts("## Turning to (");
                    uart_puts(&buff[1]);
                    uart_puts(")\r\n");
                    servo_turn(curr);
                } else {
                    uart_puts("** Invalid angle (");
                    uart_puts(&buff[1]);
                    uart_puts(")\r\n");
                }
            } else {
                uart_puts(">> ");
                uart_puts(buff);
                uart_puts("\r\n");
            }
        }
    }
}
if (G0000==0) {
    lcd_goto_line2();
    lcd_puts("ServoTurn CENTER");
    servo_turn(15);
    while (!G0000);
    lcd_goto_line2();
}

```

```

        lcd_puts("                ");
    }
    if (G01MS==0) {
        lcd_goto_line2();
        lcd_puts("ServoTurn PWM1ms");
        servo_turn(10); // 1ms pwm
        while (!G01MS);
        lcd_goto_line2();
        lcd_puts("                ");
    }
    if (G02MS==0) {
        lcd_goto_line2();
        lcd_puts("ServoTurn PWM2ms");
        servo_turn(20); // 2ms pwm
        while (!G02MS);
        lcd_goto_line2();
        lcd_puts("                ");
    }
}
/*-----*/
-----*/

```

## Code: RFID module and OLED

Testing RFID (FRC522) and OLED (ssd1306).

[test2\\_rfid.c](#)

```

/*-----*/
-----*/
#include "uart_hexascii.h"
#include "oled_ssd1306.h"
#include "cstr_hexascii.h"
#include "frc522.h"
#define APPTITLE "NMK322 RFID/OLED"
/*-----*/
-----*/
void main(void) {
    __xdata cstr_t buff; /* default: 64-bytes long */
    unsigned char temp, stat, loop, size;
    unsigned char pdat[FRC522_MAX_RXSIZE], reqa[2];
    /** initialize */
    cstr_init(&buff);
    uart_init();
    i2c_init();
    oled1306_init();
}

```

```

spi_init();
atqa = reqa;
/* initialize mf contactless card reader */
/** say something... */
uart_puts("\n-----\n");
uart_puts(APPTITLE);
uart_puts("\n-----\n\n");
oled1306_puts(APPTITLE);
temp = frc522_init();
if (!temp||temp==0xff) {
    uart_puts("** Cannot find FRC522 hardware! Aborting!\n");
    oled1306_set_cursor(5,0);
    oled1306_puts("** Hardware Error!");
    hang();
}
uart_puts("FRC522 found. Firmware version is 0x");
uart_send_hexbyte(temp);
uart_puts(".\n");
cstr_null(&buff);
cstr_append(&buff,"FW Vers: 0x");
cstr_append_hexbyte(&buff,temp);
oled1306_set_cursor(5,0);
oled1306_puts(buff.buffer);
/* main loop */
while (1) {
    stat = frc522_scan(pdat,&size);
    if (stat==FRC522_OK) {
        uart_puts("## TAG(");
        uart_send_hexbyte(stat);
        uart_puts("|");
        uart_send_hexbyte(reqa[0]);
        uart_puts(",");
        uart_send_hexbyte(reqa[1]);
        uart_puts("):");
        cstr_null(&buff);
        for (loop=0;loop<size-1;loop++) { /** UID is size-1 bytes
*/
            uart_send('[');
            uart_send_hexbyte(pdat[loop]);
            cstr_append_hexbyte(&buff,pdat[loop]);
            uart_send(']');
        }
        uart_send('\n');
        oled1306_set_cursor(2,0);
        oled1306_puts("#TAG: ");
        oled1306_puts(buff.buffer);
        loop_delay(3000);
        oled1306_clear_row(2);
    }
    else if (stat!=FRC522_ERROR_NO_TAG&&stat!=FRC522_ERROR_REQ_A) {
        uart_puts("** Scan Failed (0x");

```



```
    P2_3 = !P3_4;
    if (timer_ticked()) {
        loop++; if (loop==10) loop = 0;
        mask = (!P2_7)?0xff:0x00;
        P1 = seg7[loop] ^ mask;
        timer_tick00();
    }
}
/*-----*/
-----*/
```

## Code: gtuc51

Test code for the old GTUC51B001 development board.

gtuc51.c

```
/*-----*/
-----*/
/**
 * Demo program for gtuc51 (with io board)
 */
/*-----*/
-----*/
#include "adc0831.h"
#include "keypad_922.h"
#include "textlcd.h"
#include "utils_float.h"
/*-----*/
-----*/
/**
 * Switch & LED Interface for gtuc51 i/o board
 * - multiplexed (dual/purpose)
 * - require jumper link settings!
 */
/** SW0, SW1 => P3.3, P3.2 - LAYOUT ERROR */
__sbit __at (0xB3) SW0;
__sbit __at (0xB2) SW1;
/** LED{0-3} => P3.4-P3.7 */
__sbit __at (0xB4) LED0;
__sbit __at (0xB5) LED1;
__sbit __at (0xB6) LED2;
__sbit __at (0xB7) LED3;
/** LED{RX,TX} => P3.1, P3.0 - LAYOUT ERROR */
__sbit __at (0xB1) LEDRX;
__sbit __at (0xB0) LEDTX;
```

```

/** alias LEDX=-2 and LEDY=-1 (LEFT OF LED0) */
__sbit __at (0xB1) LEDX;
__sbit __at (0xB0) LEDY;
/*-----*/
-----*/
char display[LCD_MAX_CHAR];
unsigned char lcdi, loop;
float value;
keybyte_t keyin;
adcbyte_t check;
__bit adc, adcgo, left, demo;
/*-----*/
-----*/
#define DEMO_I0 1
#define DEMO_ADC 0
/*-----*/
-----*/
#define LOOP_COUNT 20
/*-----*/
-----*/
/* interrupt service routine for timer0 */
void timer_blink(void) __interrupt TF0_VECTOR {
    TR0 = 0; loop--;
    P1 = ~P1;
    if (loop==0) {
        if (!left) {
            loop = LED0; LED0 = LED1; LED1 = LED2; LED2 = LED3;
            LED3 = LEDX; LEDX = LEDY; LEDY = loop;
        }
        else {
            loop = LED3; LED3 = LED2; LED2 = LED1; LED1 = LED0;
            LED0 = LEDY; LEDY = LEDX; LEDX = loop;
        }
        loop = LOOP_COUNT;
    }
    TH0 = 0x4B; TL0 = 0xFD; TR0 = 1; /** 50ms */
}
/*-----*/
-----*/
/* interrupt service routine for timer1 */
void timer_goadc(void) __interrupt TF1_VECTOR {
    TR1 = 0; TH1 = 0x4B; TL1 = 0xFD;
    if (loop>0) {
        TR1 = 1; /** 50ms */
        loop--;
    }
    else {
        loop = LOOP_COUNT;
        adcgo = adc;
    }
}
}

```

```

/*-----*/
-----*/
/* interrupt service routine for int1 */
void check_switch0(void) __interrupt IE1_VECTOR {
    left = 0;
    if (lcdi<LCD_MAX_CHAR) {
        lcd_data(0x30);
        lcdi++;
    }
}
/*-----*/
-----*/
/* interrupt service routine for int0 */
void check_switch1(void) __interrupt IE0_VECTOR {
    left = 1;
    if (lcdi<LCD_MAX_CHAR) {
        lcd_data(0x31);
        lcdi++;
    }
}
/*-----*/
-----*/
/* main function */
void main(void) {
    /** initalize stuffs */
    demo = DEMO_IO; /* default... just in case */
    TMOD = 0x11; P1 = 0xFF; P3 = 0xFF;
    lcd_init();
    lcd_goto_line1();
    lcd_puts("8051 Select Demo");
    lcd_goto_line2();
    lcd_puts("[SW0]IO [SW1]ADC");
    /* wait for user key press */
    while (1) {
        if (!SW0) {
            demo = DEMO_IO; /* demo switch, led, keypad and P1 */
            while(!SW0); /* wait until the user press & let go */
            break;
        }
        else if (!SW1) {
            demo = DEMO_ADC; /* demo adc */
            while(!SW1);
            break;
        }
    }
    /* select! */
    if (demo==DEMO_IO) {
        lcd_goto_line1();
        lcd_puts("MY18051 I/O DEMO");
        lcd_goto_line2();
        lcd_puts("                ");
    }
}

```

```

    lcd_goto_line2();
    /** set timer 0 overflow every 50ms - with interrupt handler */
    loop = LOOP_COUNT; lcdi = 0; left = 0;
    P1 = 0xAA; LED0 = 0; IT0 = 1; IT1 = 1;
    EA = 1; ET0 = 1; EX0 = 1; EX1 = 1;
    TH0 = 0x4B; TL0 = 0xFD; TR0 = 1;
    /** main loop */
    while (1) {
        keyin = key_wait_922();
        if (keyin < 10 && lcdi < LCD_MAX_CHAR) { /** numeric key! */
            lcd_data(keyin + 0x30);
            lcdi++;
        }
        else if (keyin == 0x0F) { /** '#' key! */
            lcd_goto_line2();
            lcd_puts("HASHED!          ");
            lcd_goto_line2();
            lcdi = LCD_MAX_CHAR;
        }
        else if (keyin == 0x0E) { /** '*' key! */
            lcd_goto_line2();
            lcd_puts("          ");
            lcd_goto_line2();
            lcdi = 0;
        }
    }
}
else {
    lcd_goto_line1();
    lcd_puts("MY18051 ADC DEMO");
    lcd_goto_line2();
    lcd_puts("SW0:ADC, SW1:CLR");
    /** initialize adc */
    adc_init();
    adc = 0; adcgo = 0; EA = 1;
    /** adc status indicator */
    LEDRX = adc; LEDTX = !adc;
    /** main loop */
    while (1) {
        if (!SW0) {
            while (!SW0); /** wait until the user lets go */
            adc = !adc;
            adcgo = adc;
            if (!adcgo) {
                ET1 = 0; TR1 = 0;
                lcd_puts("*");
            }
            LEDRX = adc; LEDTX = !adc;
        }
        else if (!SW1) {
            while (!SW1); /** wait until the user lets go */

```

